



Finding Discriminative Filters for Specific Degradations in Blind Super-Resolution

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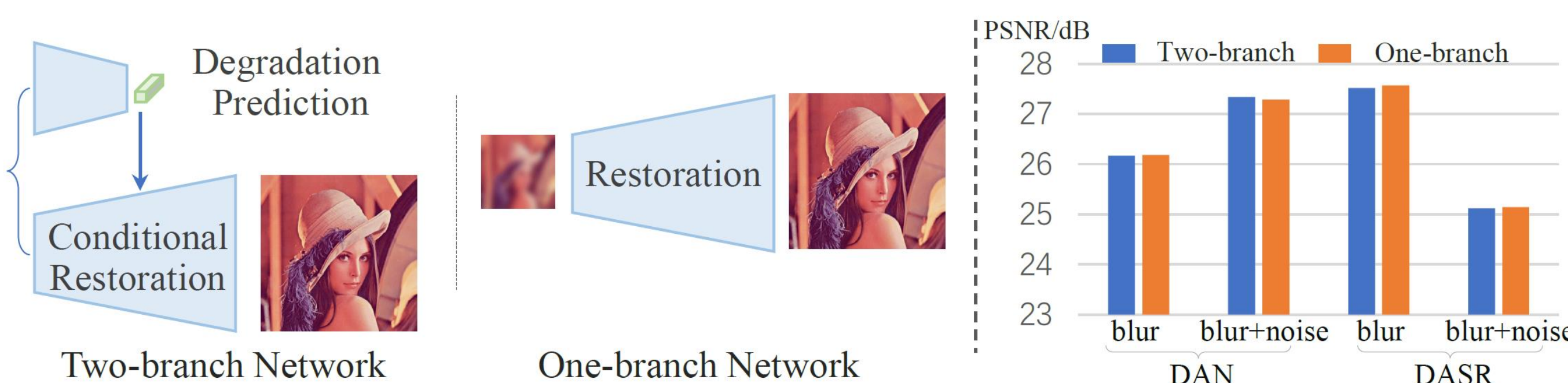
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The mechanism of Blind SR Network

Motivation

A unified one-branch network could achieve comparable performance to the two-branch scheme under similar computation budgets.

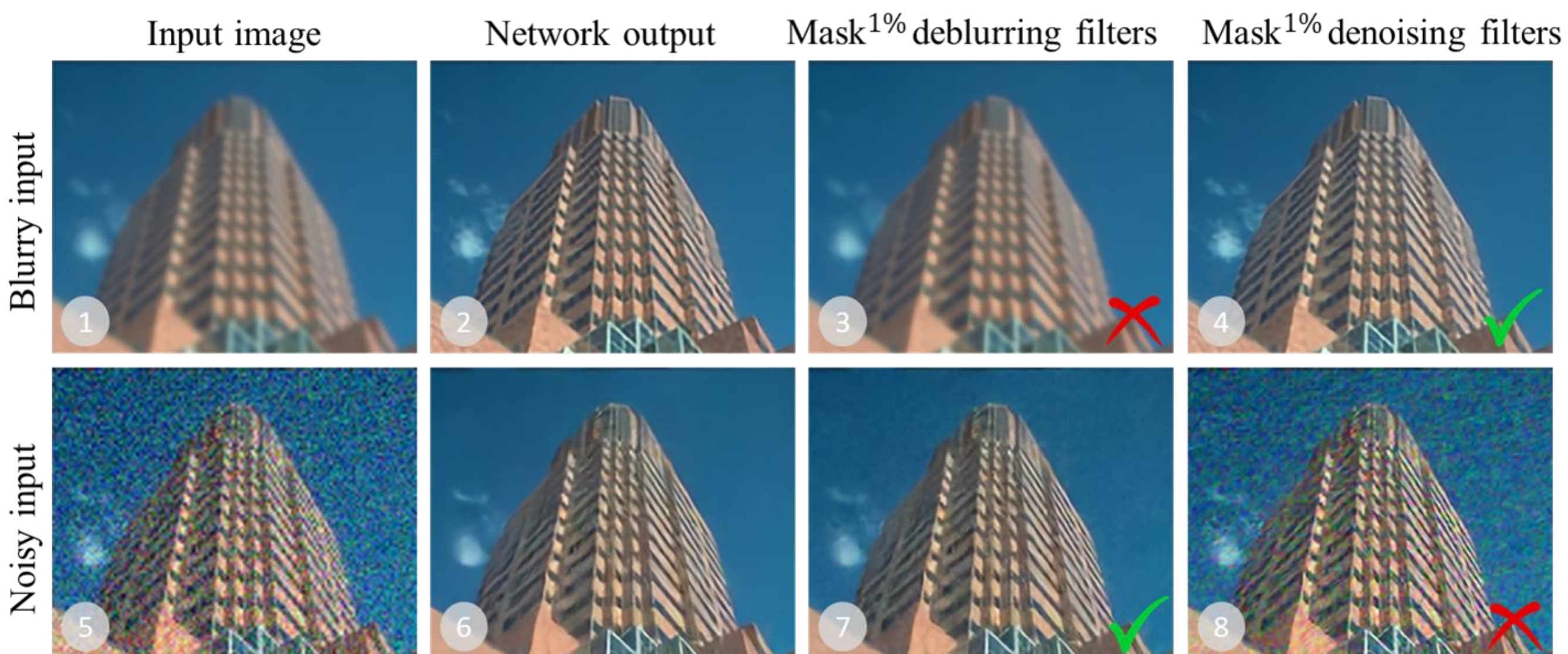


Two key questions are investigated

- Could one-branch networks automatically learn to distinguish degradations as what we specially design in two-branch methods?
- Are there any small sub-network (i.e., a set of filters) existing for a specific degradation?

A diagnostic tool—Filter Attribution Integrated Gradients (FAIG)

In this work, we propose Filter Attribution method based on Integral Gradient (FAIG) to find core filters in a network that make the greatest contribution to the function of a specific degradation removal.

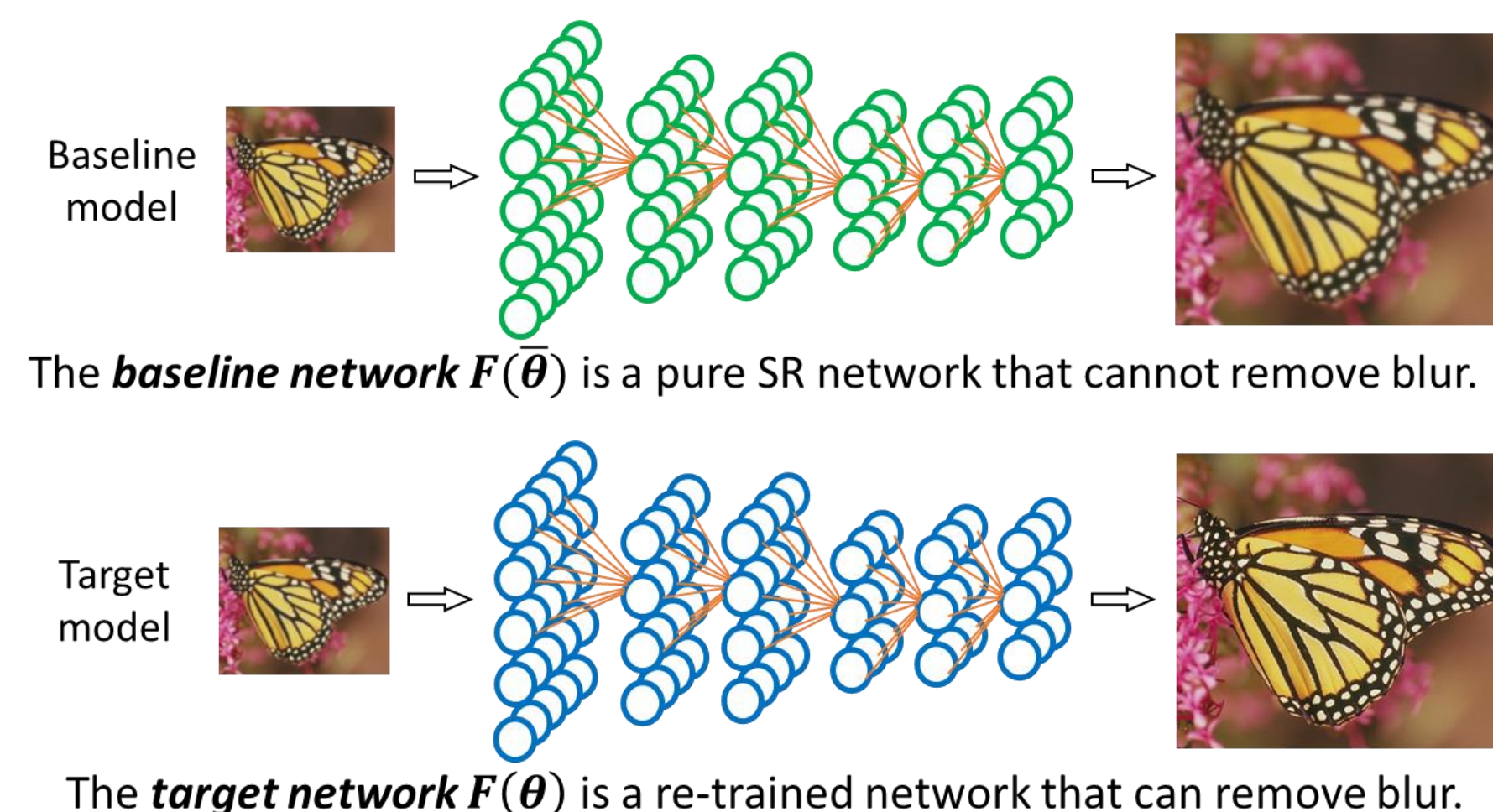


When we mask these discovered filters for a specific degradation, the corresponding function is eliminated, while functions for other degradations are maintained

Filter Attribution Integrated Gradient (FAIG)

Key idea

Given the same input, the changes of the network output can be attributed to the changes of network parameters (i.e., filters).



Find important filters for one degradation

We first quantify the network function of degradation removal by

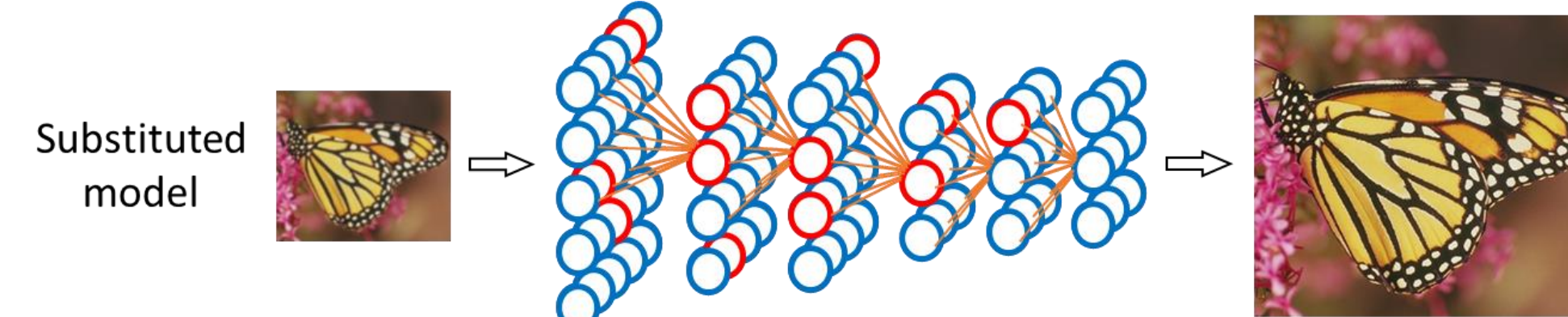
$$\mathcal{L}(\theta, x) = \|F(\theta, x) - x^{gt}\|_2^2$$

Motivated by Integrated Gradient (IG) that accumulates the gradients at all points along a straight-line path, we accumulate gradients along a path

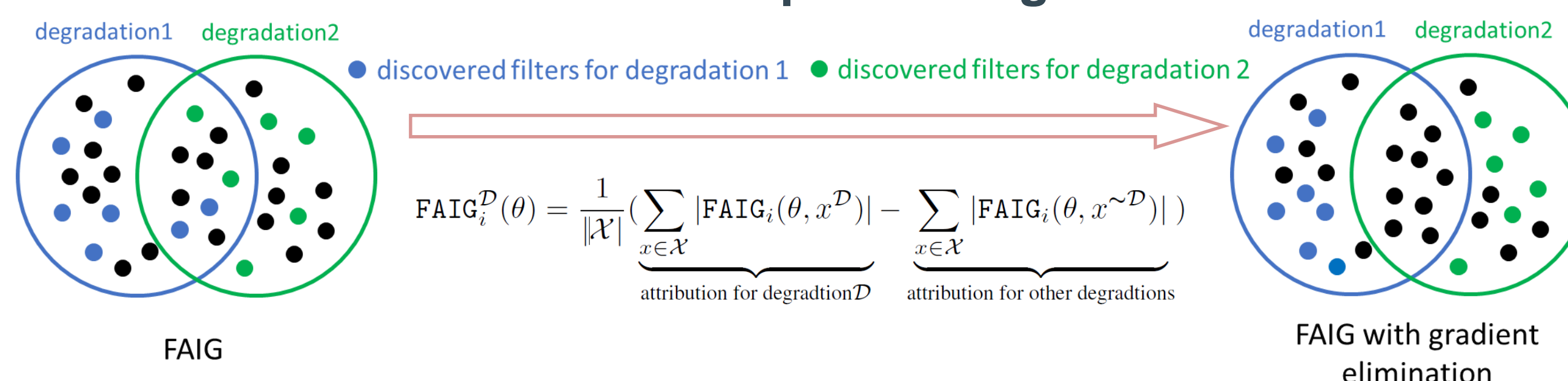
$$\gamma(\alpha) = \bar{\theta} + \alpha \times (\theta - \bar{\theta})$$

$$\text{FAIG}_i(\theta, x) = \int_{\alpha=0}^1 \frac{\partial \mathcal{L}(\gamma(\alpha), x)}{\partial \gamma(\alpha)_i} \times \frac{\gamma(\alpha)_i}{\partial \alpha} d\alpha$$

The filters with highest gradient are the most discriminative filters

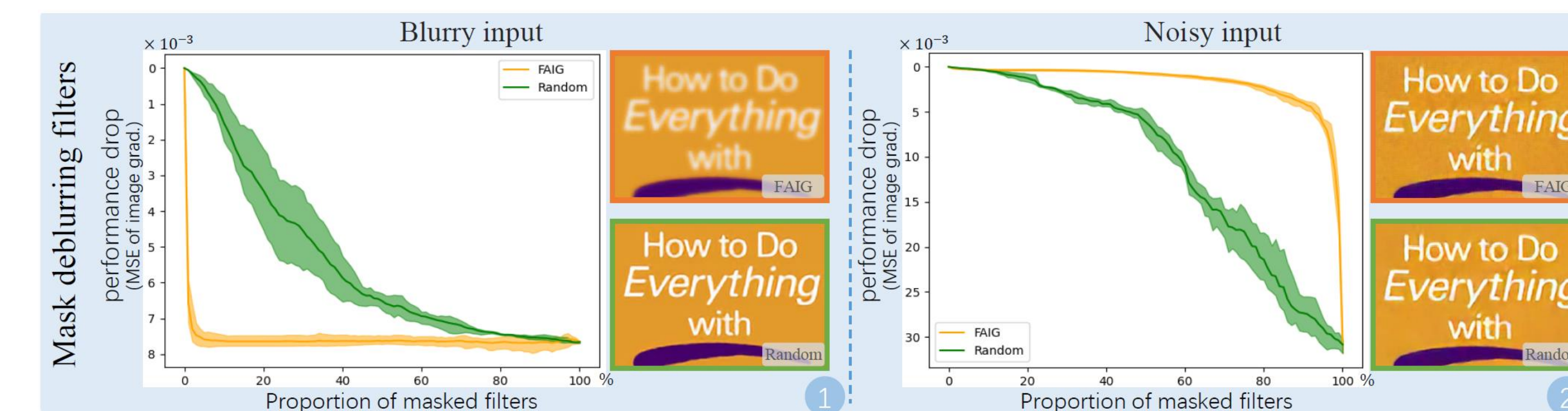


Find Discriminative filters for specific degradation



Experiments

Mask discovered filters



When we mask FAIG-discovered filters for deblurring (even a very small portion), the performance for deblurring drops drastically while the function of denoising is maintained. While the randomly selected filters are non-discriminative

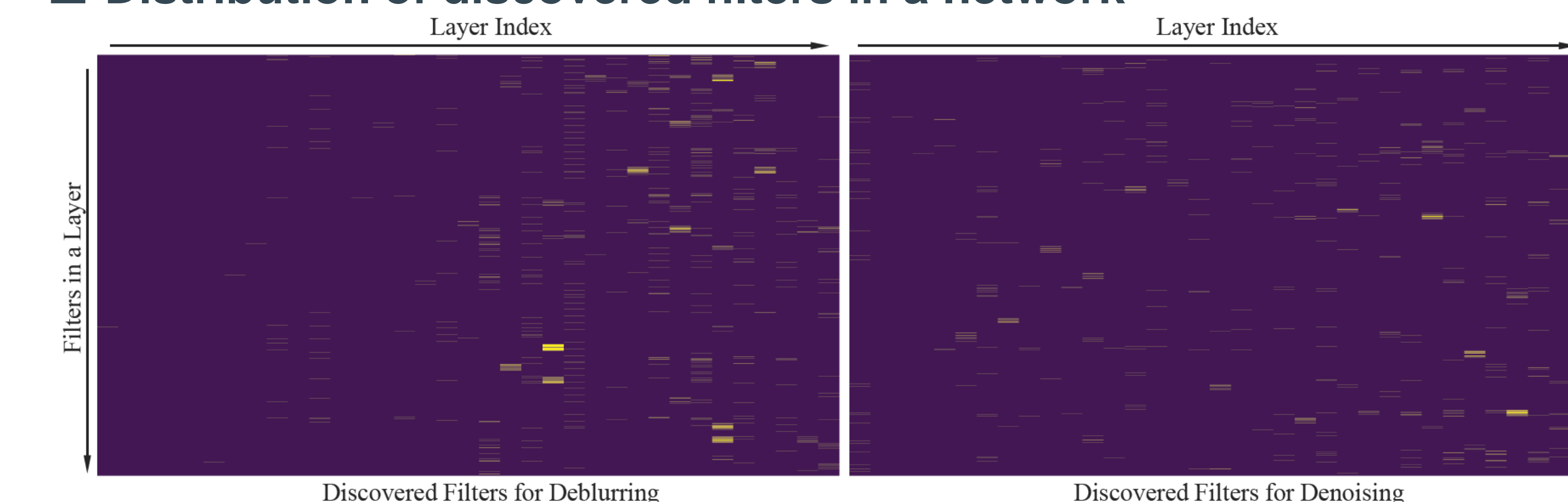
| (10 ⁻³) | mask 1% discovered filters | | | | mask 5% discovered filters | | | |
|---------------------|----------------------------|-----------|---------------------------|-----------|----------------------------|-----------|---------------------------|-----------|
| Input | FAIG (ours) | IG | $ \theta - \bar{\theta} $ | Random | FAIG (ours) | IG | $ \theta - \bar{\theta} $ | Random |
| Blurry image | 6.68±0.63 | 4.31±1.54 | 0.18±0.13 | 0.07±0.01 | 7.53±0.24 | 6.41±0.88 | 2.16±0.61 | 0.55±0.32 |
| Noisy image | 6.62±0.54 | 4.22±0.44 | 0.49±0.10 | 0.04±0.01 | 16.28±3.84 | 8.01±1.04 | 3.25±1.85 | 0.19±0.05 |

Distribution of discovered filters in a network

| PSNR(dB) | Input | Upper bound | Re-train 1% filters for deblurring | | | | Re-train 1% filters for denoising | | | |
|----------|-------|--------------------|------------------------------------|--------------------|---------------------------|--------------------|-----------------------------------|--------------------|---------------------------|--------------------|
| | | | FAIG | IG | $ \theta - \bar{\theta} $ | Random | FAIG | IG | $ \theta - \bar{\theta} $ | Random |
| Blurry | | 29.203 (±0.021) | 27.889 (±0.207) | 26.389 (±0.274) | 26.444 (±0.097) | 26.691 (±0.092) | 27.642 (±0.007) | 26.534 (±0.125) | 26.444 (±0.096) | 26.668 (±0.126) |
| | | | 26.712 (±0.008) | 25.268 (±0.035) | 25.211 (±0.005) | 25.288 (±0.044) | 25.239 (±0.034) | 25.743 (±0.033) | 25.141 (±0.116) | 25.275 (±0.035) |

The locations and connections of discovered filters also have discriminative characteristics for specific degradations

Distribution of discovered filters in a network



The deblurring filters are more located in the back part of the network while denoising filters locate more uniformly